

Phys 221 Equations Page

Quadratic formula: if $Az^2 + Bz + C = 0$, then $z = \frac{1}{2A} \left[-B \pm \sqrt{B^2 - 4AC} \right]$

constant acceleration: $\vec{x}(t) = \vec{x}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$, $\vec{v}(t) = \vec{v}_0 + \vec{a} t$
 $\vec{x}(t) = \vec{x}_0 + \frac{1}{2} (\vec{v}_0 + \vec{v}) t$ $\frac{1}{2} v_f^2 - \frac{1}{2} v_i^2 = \vec{a} \cdot (\vec{x}_f - \vec{x}_i)$

circular motion: $a_N = \frac{v^2}{r}$ (pointing inward) $a_T = \text{rate of change of speed}$

center of mass: $x_{cm} = \frac{\sum m_i x_i}{\sum m_i}$, $y_{cm} = \frac{\sum m_i y_i}{\sum m_i}$, etc. $\vec{v}_{CM} = \frac{\sum m_i v_i}{\sum m_i}$

momentum: $\vec{p} = m\vec{v}$ (and \vec{p} is conserved in the absence of external forces)
Impulse = $\int \vec{F} dt$ *Net impulse* = $\int \Sigma \vec{F} dt = \Delta \vec{p}$

force: **2nd law:** $\Sigma \vec{F} = \frac{d\vec{p}}{dt}$ or $\Sigma \vec{F} = m\vec{a}$ (if mass is constant)
3rd law: $\vec{F}_{AB} = -\vec{F}_{BA}$

work: $\text{work} = \vec{F} \cdot \Delta \vec{x} = F \Delta x \cos \theta$ (if force is constant) or $\text{work} = \int \vec{F} \cdot d\vec{x}$

kinetic energy: $K = \frac{1}{2} m v^2$

Net Work and Kinetic Energy: $\Sigma \vec{F} \cdot \Delta \vec{x} = \Delta K$ (if force is constant)

or : Work done by the net force = $\int (\Sigma \vec{F}) \cdot d\vec{x} = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \Delta K$

Gravity and potential energy: $\vec{F} = m\vec{g}$ (pointing down) and $U_{grav} = mgh + C$

Far from Earth: $F = \frac{GMm}{r^2}$ $U_{grav} = -\frac{GMm}{r} + C$

Springs and elastic potential energy: $\vec{F} = -k \vec{x}$ and $U_{elastic} = \frac{1}{2} k x^2 (+C)$

where x is measured from equilibrium.

Conservative forces: $F_{U,x} = -\frac{dU}{dx}$ $U(x) = -\int \vec{F} \cdot \overrightarrow{dx}$

kinetic friction: $f_k = \mu_k N$, (opposing the direction of motion)

static friction: $f_s \leq \mu_s N$, (opposing the direction of other forces)

Work done by kinetic friction: $Work = \vec{f}_k \cdot \Delta \vec{x}$ (usually "lost" as waste heat)

Elastic collisions: (measurements in the center of mass frame are marked with a *)

$$\vec{v}_{a,i}^* = \vec{v}_{a,i} - \vec{v}_{CM} \quad \text{and} \quad \vec{v}_{a,f} = \vec{v}_{CM} - \vec{v}_{a,i}^*$$